



RCP6 Actuator Rotary Chuck

First Step Guide First Edition

Thank you for purchasing our product.
Make sure to read the Safety Guide and detailed Instruction Manual as well as this First Step Guide to ensure correct use.
This Instruction Manual is original.

Warning: Read the instruction manual carefully and follow the instruction manual when handling this equipment. Please download the user's manual from our website. You can download it free of charge. User registration is required for first time users.
URL: www.iai-robot.co.jp/data_di/CAD_MANUAL/
Keep a printout of the introduction manual near the equipment in which this product is installed so that it can be checked at all times, or display it on your computer, tablet terminal, etc. so that you can check it immediately.
If you need a bound copy of the instruction manual, order it from the nearest sales office listed in the First Step Guide or at the end of the instruction manual. It will be provided for a fee.

- Using or copying all or part of this Instruction Manual without permission is prohibited.
- The company names, names of products and trademarks of each company shown in the sentences are registered trademarks.

Product Check

This product is comprised of the following parts if it is of standard configuration.
If you find any fault in the contained model or any missing parts, contact us or our distributor.

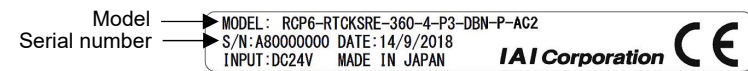
1. Parts (The option is excluded.)

No.	Part Name	Model	Quantity	Remarks
1	Rotary Chuck	Refer to "How to Read the Model Nameplate" and "How to Read the Model Number".	1	
Accessories				
2	Driver Box	Refer to "How to Read the Model Nameplate".	1	
3	Motor Encoder Integrated Cables <small>(Note1)</small>		1	
4	Solenoid Driver Cable <small>(Note1)</small>	CB-GRS-PCS□□□	1	□□□ shows the cable length 1m to 15m
5	Safety Guide	M0194	1	

Note 1 Please refer to the wiring layout for the enclosed motor encoder integrated cables and solenoid driver cable.

2. How to read the model plate

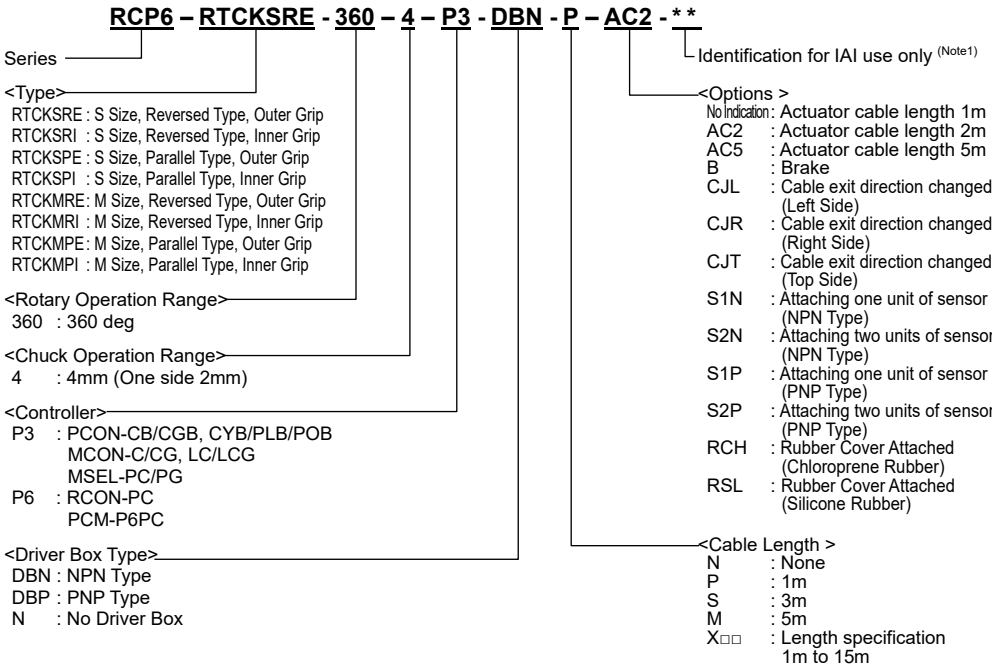
2.1 Main Body



2.2 Driver Box



3. How to read the model No.



Note 1 Identification for IAI use only: It may be displayed for IAI use. It is not a code to show the model type.

[Refer to the catalog or Instruction Manual for specification details.]

Precautions in Handling

1. Handling the Packed Unit

- Do not damage or drop. The package is not applied with any special treatment that enables it to resist an impact caused by a drop or crash.
- Keep the unit in a horizontal orientation when placing it on the ground or transporting. Follow the instruction if there is any for the packaging condition.
- Do not step or sit on the package.
- Do not put any load that may cause a deformation or breakage of the package.

2. Handling the Actuator After Unpacking

- Do not carry the actuator by its motor unit or its cable or attempt to move it by pulling the cable.
- Hold the body when transporting the actuator main body.
- Do not hit or drop the actuator during transportation.
- Do not attempt to force any part of the actuator. Do not apply excess force especially on the finger attachment.

Environments for Installation, Storage and Preservation

1. Installation Environment

Usage is possible in environments of pollution degree 3 or equivalent.

The actuator should be installed in a location other than those specified below.
Also provide sufficient work space required for maintenance inspection.

- Where the actuator receives radiant heat from strong heat sources such as heat treatment furnaces
- Where the ambient temperature exceeds the range of 0 to 40°C
- Where the temperature changes rapidly and condensation occurs
- Where relative humidity smaller than 20% or larger than 85%RH
- Where the actuator receives direct sunlight
- Where the actuator is exposed to corrosive or combustible gases
- Where the ambient air contains a large amount of powder dust, salt or iron (at level exceeding what is normally expected in an assembly plant)
- Where the actuator is subject to splashed water, oil (including oil mist or cutting fluid) or chemical solutions
- Where the actuator receives impact or vibration
- Place with an altitude of 2,000m or more

If the actuator is used in any of the following locations, provide sufficient shielding measures:

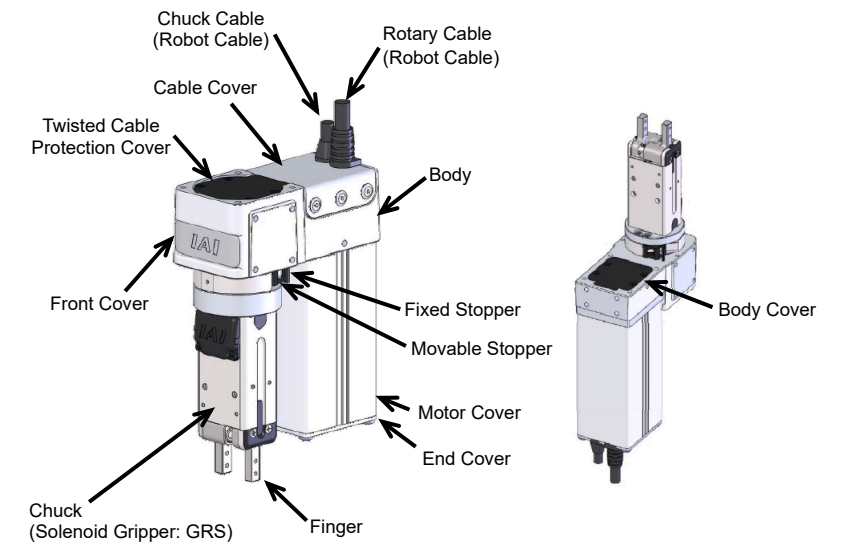
- Where noise generates due to static electricity, etc.
- Where the actuator is subject to a strong electric or magnetic field
- Where the actuator is subject to ultraviolet ray or radiation

2. Storage • Preservation Environment

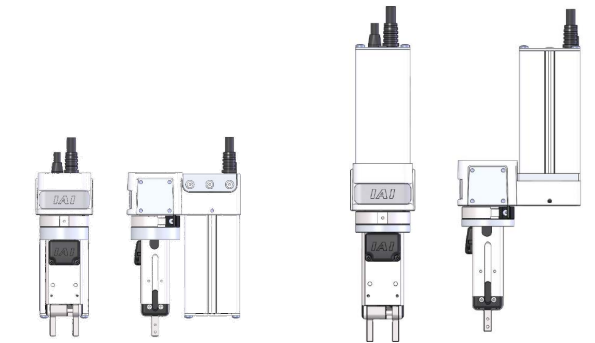
- The storage and preservation environment should comply with the same standards as those for the installation environment. In particular, when the machine is to be stored for a long time, pay close attention to environmental conditions so that no dew condensation forms.
- Unless specially specified, moisture absorbency protection is not included in the package when the machine is delivered. In the case that the machine is to be stored and preserved in an environment where dew condensation is anticipated, take the condensation preventive measures from outside of the entire package, or directly after opening the package.
- For storage and preservation temperature, the machine withstands temperatures up to 60°C for a short time, but in the case of the storage and preservation period of 1 month or more, control the temperature to 50°C or less.
- Storage and preservation should be performed in the horizontal condition. In the case it is stored in the packaged condition, follow the posture instruction if any displayed on the package.

Names of the Parts

1. Rotary Chuck Main Body

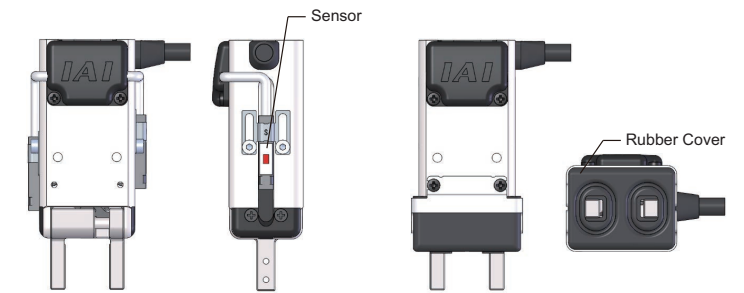


[Direction of Motor Reversed]



Reversed Type

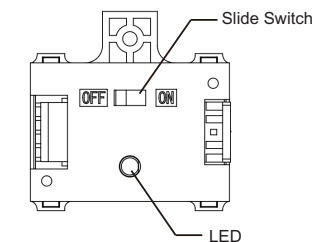
Parallel Type



Attaching Sensor (Option)

Rubber Cover (Option)

2. Driver Box



* Set this slide switch to "ON" side and the fingers on the chuck for the outer gripping type should be compulsorily open. For the inner gripping type, it should be compulsorily close. While the switch is on, the LED lamp should be on. Turn the slide switch OFF when in use.

[For the details of dimensions and outlines, refer to the catalog or Instruction Manual.]

Attachment

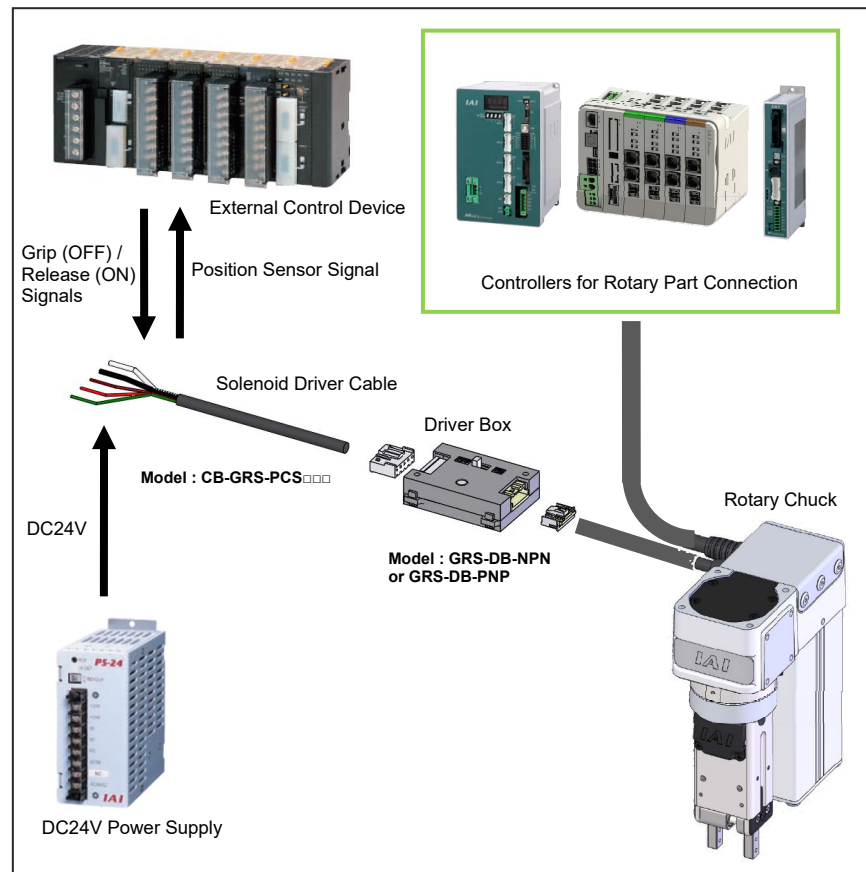
Refer to the Instruction Manual for the attachments of the actuator and loads.

[Precautions for Attachments]

No.	Item	Precautions
1	Attachment	<ul style="list-style-type: none"> The surface to install the unit should possess the flatness of machine finished or equivalent. When you have the parallel type installed with the bottom surface fixed, pay attention not to have the movable stopper of the rotating chuck interfere with anything in the operation range. Temperature of the chuck should rise when it makes a releasing operation as the current flows when it releases. If a workpiece has a concern of temperature influence, consider to use a resin with low heat conductivity for the chuck. Have enough space for the maintenance work.
2	Bolt to be used	<ul style="list-style-type: none"> For the bolts to be used, a high-tensile bolt complying with ISO-10.9 or more is recommended. If using the tapped holes, use screws with the thread length dimension being less than the effective depth of the holes. Ensure to have one time or more of the nominal diameter for the length of thread engagement between the screw used for actuator attachment and the tapped hole.
3	Tightening Torque	<ul style="list-style-type: none"> Please follow the specification values stated in the Instruction Manual for the tightening torque. Failure to do so may cause an operation problem.
4	Allowable Moment Overhang Amount	<ul style="list-style-type: none"> Make sure to have the allowable moment of inertia and the overhang amount below the maximum allowable moment of inertia and the maximum amount of overhang described in the instruction manual. Applying load exceeding the maximum allowable moment of inertia or maximum amount of overhang may shorten the product life.

Wiring

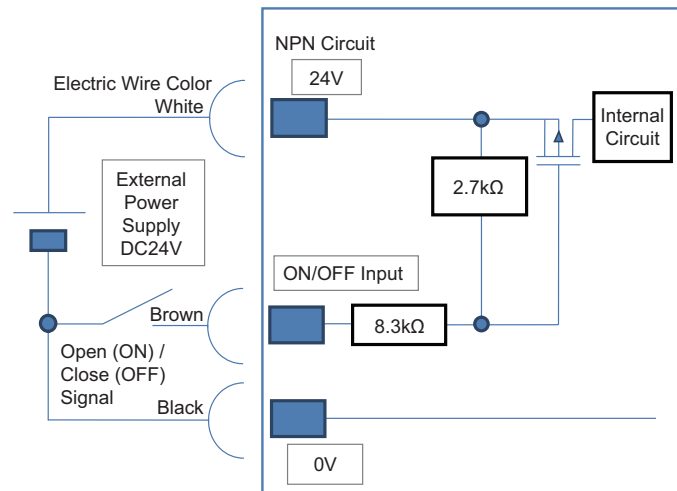
The following shows the system configuration.



Supply 24V DC in the circuit shown below. Outer gripping type should open and close the fingers when it inputs Open (ON) / Close (OFF) Signals. The inner grip type works in the other way.

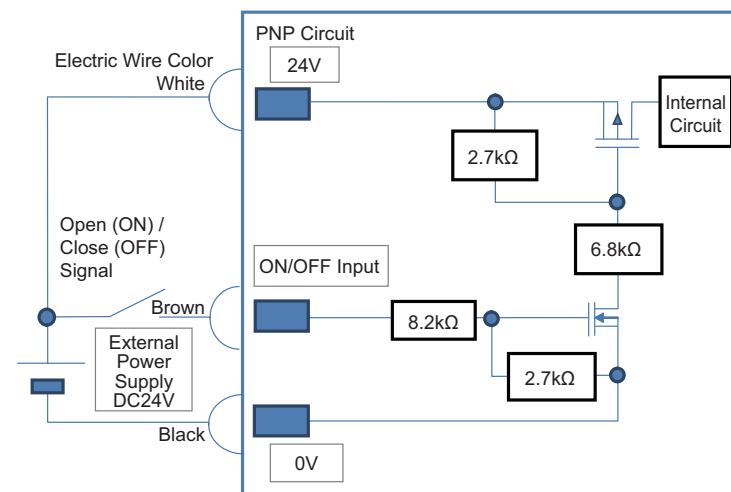
[NPN Type]

Item	Specifications
Input voltage	DC24V±10%
Input current	2mA
Leakage current	Max. 0.25mA
Operation Voltage	ON voltage : Max. 6.0V
	OFF voltage : Input voltage Min. -3.0V
Isolation type	Non-isolated

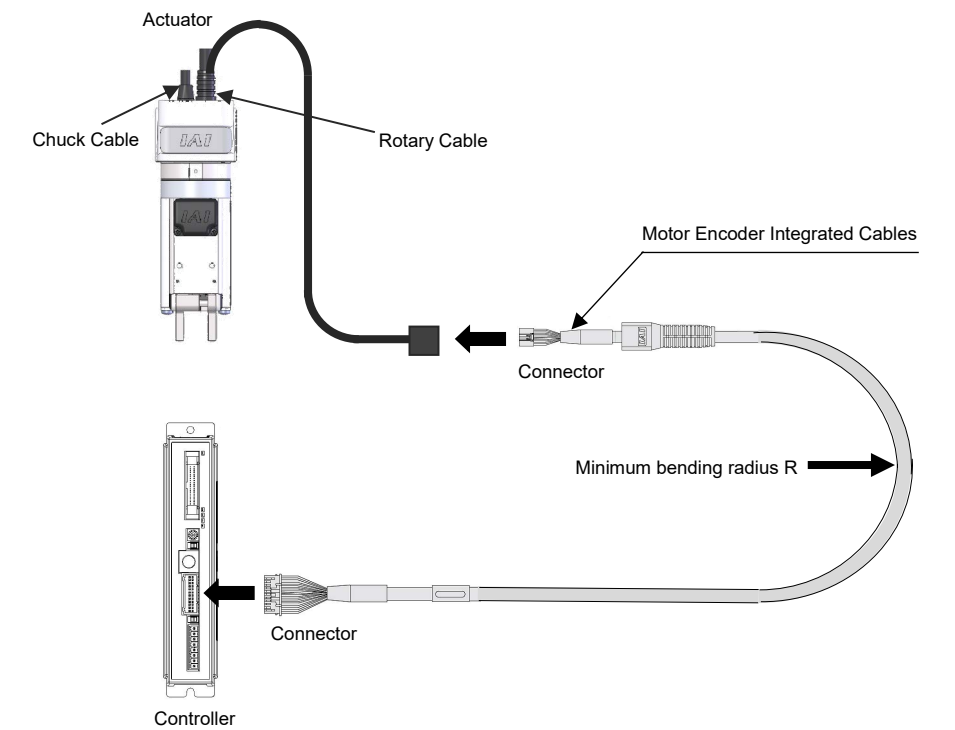


[PNP Type]

Item	Specifications
Input voltage	DC24V±10%
Input current	2mA
Leakage current	Max. 0.25mA
Operation Voltage	ON voltage : Min. 18.0V
	OFF voltage : Input voltage Max. 3.0V
Isolation type	Non-isolated



Wiring between Rotary Part and Controller



[List of Connection Cable between Actuator and Controller]

Controller Model	Motor Encoder Integrated Cables					
	Standard Cable (Fixed Use)			Robot Cable (Movable Use)		
	Model (Note1)	Min. bending radius R [mm]		Model (Note1)	Min. bending radius R [mm]	
		5m or less	5m and above		5m or less	5m and above
PCON-CB/CGB PCON-CYB/PLB/POB PCON-CFB/CGFB MCON MSEL	CB-CAN-MPA□□□	85 or more	91 or more	CB-CAN-MPA□□□-RB	68 or more	73 or more
RCON RCM-P6PC	CB-ADPC-MPA□□□	85 or more	91 or more	CB-ADPC-MPA□□□-RB	68 or more	73 or more

Note1 □□□ indicates the cable length. Example) 080 = 8m Up to 20m can be specified.

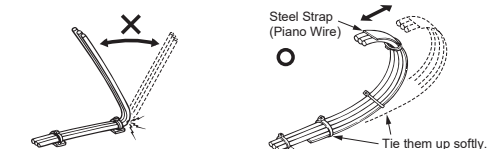
For the controller, only the dedicated controller manufactured by our company can be used. For the connection between the rotary chuck and a controller, use the enclosed dedicated connection cable. For the driver box, no driver box other than IAI dedicated driver box should be available to use. Using an undedicated connection cable and driver box may cause an accident such as burnout, combustion or heat generation.

Use the dedicated cable enclosed in the package when connecting the actuator and the driver box.

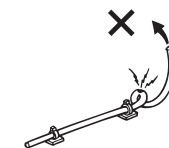
[Prohibited Items in the Cable Processing]

- Do not pull or bend forcibly the cable so as to give any extra load or tension to the cable.
- Do not process the cable to extend or shortening by means of cutting out, combination or connecting with another cable.

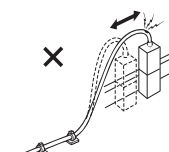
- Do not let the cable flex at a single point.



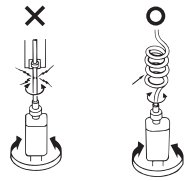
- Do not let the cable bend, kink or twist.



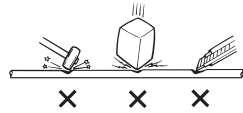
- Do not pull the cable with a strong force.



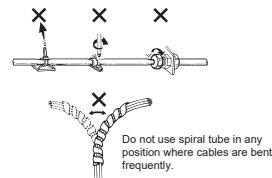
- Do not let the cable receive a turning force at a single point.



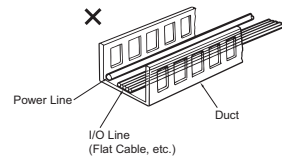
- Do not pinch, drop a heavy object onto or cut the cable.



- When fixing the cable, provide a moderate slack and do not tension it too tight.

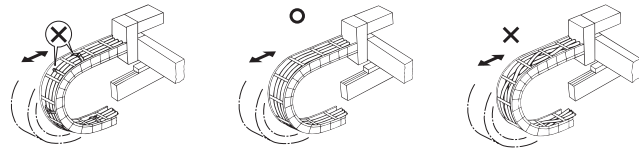


- Separate the I/O line, communication line and power line from each other. Do not store in the same duct.



Follow the instructions below when using a cable track.

- If there is an indication to the cable for the space factor in a cable track, refer to the wiring instruction given by the supplier when storing the cable in the cable track.
- Avoid the cables to get twined or twisted in the cable track, and also to have the cables move freely and do not tie them up. (Arrange the wiring so the cables are not to be pulled when bent.) Do not pile up cables. It may cause faster abrasion of the sheaths or cable breakage.



- Note:**
- When the cable is connected or disconnected, make sure to turn off the power. When the cable is connected or disconnected with the controller power turned ON, it might cause a malfunction of the actuator and result in a serious injury or damage to the machinery.
 - When the connector connection is not correct, it would be dangerous because of a malfunction of the actuator. Make sure to confirm that the connector is connected correctly.



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